





An improved correction method for field measurements of particulate light backscattering in turbid waters

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Interests

The the **seawater reflectance** signal (Rrs, sr⁻¹), is function of two inherent optical properties (IOPs): the **absorption** (a, m⁻¹) and **backscattering** (b_b , m⁻¹) coefficients (Gordon et al. 1975; Morel and Prieur 1977)

Rrs = Lu (0-) / Ed (0-) =
$$f/Q \times b_b / (a + b_b)$$

Where: Lu (0-) and Ed (0-) are the upwelling radiance and downwelling irradiance just below the sea surface; f/Q is the proportionality factor

State of the Art

No (very few?) field measurement of b_{bp} in turbid coastal/estuarine waters(!) as sensors designed and used in marine optics either:

- Saturate in highly scattering waters (ECO-BB, Wetlabs)¹
- Do not have proper correction for light attenuation (**Hydroscat, Hobilabs**)²





[1] measures light backscattered at 117°
Fixed gain / sensitivity for open ocean

[2] measures light backscattered at 140° Adaptative gain: clear to turbid waters

State of the Art

- → Use of Hydroscat in turbid estuarine waters (SeaSWIR)
 - Each sensor is calibrated in pure water
 - Need to correct for other absorption and scattering losses
 - Need to measure a and b (e.g., AC₇9 meter, Wetlabs)



State of the Art

 \rightarrow The sigma-correction (Hydroscat)

$$\beta = \sigma(K_{bb}) \cdot \beta_u$$

$$\sigma(K_{bb}) = \exp(k_{exp}K_{bb})$$

 $K_{bb} = a + 0.4b$ With 0.4 coming from ...???



- Check the validity of the sigma correction
- Improve/modify the correction method in the case of highly-turbid and scattering waters
- Test it on a representative dataset
- Validate the new method



Methods

The SimulO 3D Monte Carlo code (Leymarie et al. 2010) is used to reproduce the design of the Hydroscat sensor and compare true and 'measured' β signals.



Methods



simulated IOPs

Particulate VSF: Petzold, Fournier-Forand $(b_{bp}/b_p = 0.5, 1, 2, 3, 4, 5\%)$





Field dataset



Methods



(Computations made by B. Nechad)





New correction





Conclusions

- The sigma correction method (Hydroscat backscattering sensor) not valid in turbid sediment-dominated waters: overestimation (by factor 2 to 10) of light attenuation then of corrected b_{bp} coefficient
- Light attenuation from light source to detector is actually a function of b_{bp}/b_p (as demonstrated using SimulO)
- A new correction method is proposed and requires ancillary measurements: a and b_p
- The method has been tested on SeaSWIR dataset (Rio de La Plata) and has been validated based on optical closure (*Rrs*)

Perspectives

- Improvements in Hydroscat sensor modelling in SimulO
- Application to other field datasets:
 - Bay of Bourgneuf (France) 31 stations (in process)
 - Gironde or Scheldt (new SeaSWIR campaigns?)
 - archived: Mackenzie River plume
- Retrieval of SPM size distribution from b_{bp} & *Rrs* spectral slopes?